

# Solutions to the Homework in Lecture 12

## Fundamentals of Observational Cosmology

These notes provide worked solutions to the homework problems in Lecture 12. For Problem 2, a standalone Julia script is also included in the file `lecture12_weighted_paircounts.jl`.

### Problem 1. Effective volume

**Question.** Starting from the FKP weight, derive  $V_{\text{eff}}(k)$  and explain the limiting behaviour when  $\bar{n}P \gg 1$  and when  $\bar{n}P \ll 1$ .

**Solution.** In the lecture, the shell-averaged power-spectrum variance is written schematically as

$$\frac{\sigma_P^2(k)}{P^2(k)} = \frac{(2\pi)^3 \int d^3r \bar{n}^4(\mathbf{r}) w^4(\mathbf{r}) \left[1 + \frac{1}{\bar{n}(\mathbf{r})P(k)}\right]^2}{V_k \left[\int d^3r \bar{n}^2(\mathbf{r}) w^2(\mathbf{r})\right]^2}.$$

The FKP weight that minimizes this expression is

$$w_{\text{FKP}}(\mathbf{r}) = \frac{1}{1 + \bar{n}(\mathbf{r})P(k)}.$$

Insert this weight into the variance formula. In the numerator,

$$\begin{aligned} \bar{n}^4 w_{\text{FKP}}^4 \left(1 + \frac{1}{\bar{n}P}\right)^2 &= \frac{\bar{n}^4}{(1 + \bar{n}P)^4} \frac{(1 + \bar{n}P)^2}{(\bar{n}P)^2} \\ &= \frac{\bar{n}^2}{(1 + \bar{n}P)^2} \frac{1}{P^2}. \end{aligned}$$

The denominator contains

$$\bar{n}^2 w_{\text{FKP}}^2 = \frac{\bar{n}^2}{(1 + \bar{n}P)^2}.$$

Therefore

$$\frac{\sigma_P^2(k)}{P^2(k)} \propto \frac{(2\pi)^3}{V_k} \left[ \int d^3r \frac{\bar{n}^2(\mathbf{r}) P^2(k)}{[1 + \bar{n}(\mathbf{r})P(k)]^2} \right]^{-1}.$$

This motivates the definition

$$\boxed{V_{\text{eff}}(k) = \int d^3r \left[ \frac{\bar{n}(\mathbf{r})P(k)}{1 + \bar{n}(\mathbf{r})P(k)} \right]^2}.$$

With this definition, the usual Gaussian result is written as

$$\text{Var}[\hat{P}(k)] \simeq \frac{2(2\pi)^3}{V_k V_{\text{eff}}(k)} P^2(k),$$

or equivalently

$$N_{\text{mode}}(k) \simeq \frac{V_k V_{\text{eff}}(k)}{(2\pi)^3}, \quad \frac{\sigma_P(k)}{P(k)} \simeq \sqrt{\frac{2}{N_{\text{mode}}(k)}}.$$

So  $V_{\text{eff}}$  is the volume of an ideal uniform survey that would give the same statistical power as the real inhomogeneous survey.

**Limit 1:**  $\bar{n}P \gg 1$ . In a dense region,

$$\frac{\bar{n}P}{1 + \bar{n}P} \rightarrow 1,$$

so the integrand tends to unity. Hence

$$V_{\text{eff}}(k) \rightarrow \int d^3r = V_{\text{survey}}.$$

This is the cosmic-variance-dominated regime. Once the galaxy density is high enough, adding more galaxies hardly helps; the survey is already using nearly all of its geometric volume.

**Limit 2:**  $\bar{n}P \ll 1$ . In a sparse region,

$$\frac{\bar{n}P}{1 + \bar{n}P} \approx \bar{n}P,$$

so

$$V_{\text{eff}}(k) \approx \int d^3r [\bar{n}(\mathbf{r})P(k)]^2.$$

If  $\bar{n}$  is roughly constant over a region of volume  $V$ , this becomes

$$V_{\text{eff}}(k) \approx (\bar{n}P)^2 V \ll V.$$

This is the shot-noise-dominated regime. Such regions contribute little to the measurement because there are too few galaxies to beat the Poisson noise.

So the physical meaning is very clear: the factor

$$\left[ \frac{\bar{n}P}{1 + \bar{n}P} \right]^2$$

measures how useful each volume element is for estimating  $P(k)$ .

## Problem 2. Anisotropic pair counts

**Question.** Write pseudo-code for measuring  $DD(s, \mu)$ ,  $DR(s, \mu)$  and  $RR(s, \mu)$  using weighted pair counts.

**Solution.** For weighted anisotropic pair counts, the definitions are

$$DD(s, \mu) = \frac{\sum_{i < j \in D} w_i w_j \Theta_{ij}(s, \mu)}{\sum_{i < j \in D} w_i w_j}, \quad DR(s, \mu) = \frac{\sum_{i \in D} \sum_{j \in R} w_i w_j \Theta_{ij}(s, \mu)}{\sum_{i \in D} \sum_{j \in R} w_i w_j},$$

$$RR(s, \mu) = \frac{\sum_{i < j \in R} w_i w_j \Theta_{ij}(s, \mu)}{\sum_{i < j \in R} w_i w_j},$$

where  $\Theta_{ij}(s, \mu) = 1$  if the pair lies in the chosen  $(s, \mu)$  bin and 0 otherwise.

A direct Julia-style pseudocode implementation is:

```
# Inputs:
# data_xyz    :: Nd x 3 array of Cartesian positions
# rand_xyz    :: Nr x 3 array of Cartesian positions
# w_data      :: length-Nd vector of weights
# w_rand      :: length-Nr vector of weights
# s_edges     :: bin edges in separation
# mu_edges    :: bin edges in mu (usually from 0 to 1)
```

```

initialize DD_hist[ns, nm] = 0
initialize DR_hist[ns, nm] = 0
initialize RR_hist[ns, nm] = 0

norm_DD = 0.5 * ((sum(w_data))^2 - sum(w_data.^2))
norm_DR = 0.5 * ((sum(w_rand))^2 - sum(w_rand.^2))
norm_DR = sum(w_data) * sum(w_rand)

# DD pairs
for i in 1:(Nd-1)
    for j in (i+1):Nd
        s_vec = data_xyz[j, :] - data_xyz[i, :]
        s      = norm(s_vec)
        n_vec = data_xyz[j, :] + data_xyz[i, :]
        mu     = abs(dot(s_vec, n_vec) / (norm(s_vec) * norm(n_vec)))
        (is, im) = find_bin_indices(s, mu, s_edges, mu_edges)
        if (is, im) is a valid bin
            DD_hist[is, im] += w_data[i] * w_data[j]
        end
    end
end

# DR pairs
for i in 1:Nd
    for j in 1:Nr
        s_vec = rand_xyz[j, :] - data_xyz[i, :]
        s      = norm(s_vec)
        n_vec = rand_xyz[j, :] + data_xyz[i, :]
        mu     = abs(dot(s_vec, n_vec) / (norm(s_vec) * norm(n_vec)))
        (is, im) = find_bin_indices(s, mu, s_edges, mu_edges)
        if (is, im) is a valid bin
            DR_hist[is, im] += w_data[i] * w_rand[j]
        end
    end
end

# RR pairs
for i in 1:(Nr-1)
    for j in (i+1):Nr
        s_vec = rand_xyz[j, :] - rand_xyz[i, :]
        s      = norm(s_vec)
        n_vec = rand_xyz[j, :] + rand_xyz[i, :]
        mu     = abs(dot(s_vec, n_vec) / (norm(s_vec) * norm(n_vec)))
        (is, im) = find_bin_indices(s, mu, s_edges, mu_edges)
        if (is, im) is a valid bin
            RR_hist[is, im] += w_rand[i] * w_rand[j]
        end
    end
end

DD = DD_hist / norm_DD
DR = DR_hist / norm_DR
RR = RR_hist / norm_RR

xi = (DD - 2 .* DR + RR) ./ RR    # anisotropic Landy-Szalay estimator

```

Some comments help interpret this algorithm:

- For each pair, the separation is  $\mathbf{s} = \mathbf{x}_2 - \mathbf{x}_1$ , the midpoint line of sight is  $\hat{\mathbf{n}} = (\mathbf{x}_1 + \mathbf{x}_2) / |\mathbf{x}_1 + \mathbf{x}_2|$ , and  $\mu = \hat{\mathbf{s}} \cdot \hat{\mathbf{n}}$ .
- The pair weight is the product  $w_i w_j$ . In practice each object weight may already include systematic, close-pair, redshift-failure, FKP, and possibly redshift weights.

- The normalizations make the histograms dimensionless and match the usual Landy-Szalay conventions.
- For a real survey one does *not* keep the brute-force loops; instead one uses a kd-tree or another accelerated search. The counting logic, however, is exactly the same.

I also provide a standalone Julia file, `lecture12_weighted_paircounts.jl`, that implements the same logic in a compact pedagogical script.

### Problem 3. Effective redshift

**Question.** Explain why a sign-changing redshift weight should be compared to a redshift-weighted model rather than to a model evaluated at one effective redshift.

**Solution.** For an ordinary unweighted measurement, it is often reasonable to summarize the sample by a single pair-weighted effective redshift. But a redshift-weighted measurement is not, in general, the same thing as an unweighted measurement performed at one special redshift.

The reason is that the measured statistic is a *weighted integral* over the full redshift range:

$$M_w = \frac{1}{N} \int d\mathcal{W}(z) w(z) M(z),$$

where  $M(z)$  is the theoretical model and  $d\mathcal{W}(z)$  includes the pair-weighting and inverse-variance factors. The correct theory prediction is therefore the *same weighted integral* applied to the model.

If one tries to define a single effective redshift by

$$z_{\text{eff}} = \frac{\int d\mathcal{W}(z) w(z) z}{\int d\mathcal{W}(z) w(z)},$$

problems appear as soon as  $w(z)$  changes sign:

- the denominator can become very small, so  $z_{\text{eff}}$  becomes unstable or even undefined;
- positive and negative parts of the weight cancel, so the resulting number does not tell you where the information really comes from;
- even if  $z_{\text{eff}}$  is finite, there is generally no single redshift  $z_*$  for which  $M_w = M(z_*)$ .

The last point is easiest to see by Taylor expanding the model around a pivot redshift  $z_p$ :

$$M(z) = M(z_p) + M'(z_p)(z - z_p) + \frac{1}{2}M''(z_p)(z - z_p)^2 + \dots$$

Then the weighted measurement becomes

$$M_w = A_0 M(z_p) + A_1 M'(z_p) + \frac{1}{2} A_2 M''(z_p) + \dots,$$

with moments

$$A_n = \frac{1}{N} \int d\mathcal{W}(z) w(z) (z - z_p)^n.$$

For sign-changing weights, the zeroth moment  $A_0$  can be small or vanish, while  $A_1$  or  $A_2$  is deliberately made important. In other words, such weights are designed to measure *gradient* or *curvature* information across redshift, not just an average value at one redshift.

Therefore the correct comparison is

$$M_w = \frac{1}{N} \int d\mathcal{W}(z) w(z) M(z),$$

not

$$M(z_{\text{eff}}).$$

A single effective redshift is at best a rough mnemonic; it is not the correct theory prediction when the redshift weight changes sign.